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# Hyperbolic Quadrature Method of Moments for the one-dimensional kinetic equation

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# Considered kinetic model

### Kinetic model on $f(t, \mathbf{x}, \mathbf{v})$

$$\underbrace{\partial_t f + \partial_{\mathbf{X}} \cdot (\mathbf{V} f)}_{\text{physical transport}} = \underbrace{\mathcal{S}(f)}_{\text{Source terms}}$$

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Kinetic model on  $f(t, \mathbf{x}, \mathbf{v})$   $\underbrace{\partial_t f + \partial_{\mathbf{x}} \cdot (\mathbf{v} f)}_{\text{physical transport}} = \underbrace{\mathcal{S}(f)}_{\text{Source terms}}$ Gas dynamics for example BGK source term:  $\mathcal{S}(f) = -\frac{f - f_{eq}}{Kn}$ Transition regime : 0.01 < Kn < 10Far from the Maxwellian equilibrium

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### Gas dynamics

for example BGK source term: 
$$S(f) = -\frac{f - f_{ec}}{Kn}$$
  
Transition regime : 0.01 <  $Kn$  < 10

Far from the Maxwellian equilibrium

### Population of inertial particles in a gas

for example drag source term: 
$$S(f) = -\partial_{\mathbf{v}} \cdot \left(\frac{\mathbf{v}_g(t, \mathbf{x}) - \mathbf{v}}{St}f\right)$$

Particle trajectory crossing for large enough particles (and St): f is no more a Dirac delta function

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Particle trajectory crossing for large enough particles (and St): f is no more a Dirac delta function

- The kinetic model is too costly to solve with direct methods of Monte-Carlo type
- Moments  $\int_{\mathbb{R}} v^k f(t, \mathbf{x}, \mathbf{v}) d\mathbf{v}$  of order k smaller than 1 or 2 are not enough to represent the distribution.

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# Moment method

### Principle of the method

Write equations on a finite set of moments  $\mathbf{m}_N = (m_0, m_1, \dots, m_N)^t$ :

$$\partial_t m_k + \partial_x m_{k+1} = \mathcal{S}_k, \qquad k = 0, 1, \dots, N$$
 (1)

**Closure**: express  $m_{N+1}$  (and eventually the source terms  $S_k$ ) as a function of  $\mathbf{m}_N$ .

Issues:

- $(m_0, m_1, \ldots, m_N, m_{N+1})^t$  is realizable
- The system (1) is globally hyperbolic
- Capture equilibrium state

### Strategy

Solve the Hamburger truncated moment problem:

find a positive measure  $\mu$  such that  $\mathbf{m}_N = \int_{\mathbb{T}} (1, v, \dots, v^N)^t d\mu(v)$ .

and set  $\mathit{m}_{N+1} = \int_{\mathbb{R}} \mathit{v}^{N+1} \mathrm{d} \mu(\mathit{v})$ 

Give directly m<sub>N+1</sub>

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### Examples of closure in the literature

- Grad closure [Grad, 1949]
   → hyperbolic only around the moments of the maxwellian distribution
- Entropy maximization [Levermore, 1996, Müller and Ruggeri, 1998] → high computational cost - not valid on the entire realizability domain
- Quadrature method of moment [McGraw, 1997, Fox, 2008] → weakly hyperbolic

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# Moment space

### Definition

The  $n^{th}$ -moment space  $\mathcal{M}_n$  is defined by

$$\mathcal{M}_n = \left\{ \mathbf{m} \in \mathbb{R}^{n+1} \mid \exists \mu \in \mathcal{M}_+(\mathbb{R}), \quad \mathbf{m} = \int_{\mathbb{T}} (1, v, \dots, v^n)^t d\mu(v) \right\}$$

If **m** belongs to  $\dot{\mathcal{M}}_n$ , then it is said to be <u>realizable</u>. If **m** belongs to the interior Int  $\mathcal{M}_n$  of  $\mathcal{M}_n$ , it is said to be strictly realizable.

Characterized by the non-negativity of the **Hankel determinants**:  $n \ge 0$ 

$$\underline{H}_{2n} = \left| \begin{array}{ccc} m_0 & \dots & m_n \\ \vdots & & \vdots \\ m_n & \dots & m_{2n} \end{array} \right|$$

### Theorem

 $\mathbf{m}_N = (m_0, m_1, \dots, m_N)^t \text{ strictly realizable} \Leftrightarrow \underline{H}_{2k} > 0, \quad k \in \{0, 1, \dots, \left\lfloor \frac{N}{2} \right\rfloor \}$ 

$$\mathbf{m}_{N} \in \partial \mathcal{M}_{N} \cap \mathcal{M}_{n} \Rightarrow \underline{H}_{0} > 0, \dots, \underline{H}_{2k-2} > 0, \underline{H}_{2k} = 0, \dots, \underline{H}_{2\left\lfloor \frac{N}{2} \right\rfloor} = 0, \, k \leq \left\lfloor \frac{N}{2} \right\rfloor.$$

In the latter case, the only corresponding measure is a sum of k weighted Dirac delta functions.

[Shohat and Tamarkin, 1943, Gautschi, 2004, Schmüdgen, 2017]

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Characterized by the non-negativity of the <u>Hankel determinants</u>:  $n \ge 0$ 

$$\underline{\mathcal{H}}_{2n} = \left| \begin{array}{ccc} m_0 & \dots & m_n \\ \vdots & & \vdots \\ m_n & \dots & m_{2n} \end{array} \right|,$$

First constraints for the strict realizability:

$$m_0 > 0 \qquad m_2 > \frac{m_1^2}{m_0}$$
$$m_4 > \frac{m_0 m_3^2 - 2m_1 m_2 m_3 + m_2^3}{m_2 m_0 - m_1^2}$$

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# Characteristic polynomial

### System on moments

Equations on  $\mathbf{m}_N = (m_0, m_1, \dots, m_N)^t$ :

$$\partial_t \mathbf{m}_N + \partial_x F(\mathbf{m}_N) = \overline{S}$$

### Characteristic Polynomial

Jacobian matrix

$$\frac{D\mathbf{F}(\mathbf{m}_N)}{D\mathbf{m}_N} = \begin{pmatrix} 0 & 1 & 0 & \dots & 0\\ 0 & 0 & 1 & & 0\\ \vdots & & \ddots & \ddots & \vdots\\ 0 & 0 & 0 & 0 & 1\\ \frac{\partial m_{N+1}}{\partial m_0} & \frac{\partial m_{N+1}}{\partial m_1} & \frac{\partial m_{N+1}}{\partial m_2} & \dots & \frac{\partial m_{N+1}}{\partial m_N} \end{pmatrix}$$

Characteristic polynomial

$$\overline{P}_{N+1}(X) = X^{N+1} - \sum_{i=0}^{N} \frac{\partial m_{N+1}}{\partial m_i} X^i$$

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# Moments - Central moments - Standardized moments

moments:

$$m_k = \int_{\mathbb{R}} v^k f(v) \mathrm{d} v$$

<u>central moments</u>: with  $\rho = m_0$ ,  $u = \frac{m_1}{m_0}$  and  $f^c(c) = \frac{1}{\rho}f(c+u)$ 

$$C_k = \frac{1}{\rho} \int_{\mathbb{R}} (v - u)^k f(v) \mathrm{d}v = \int_{\mathbb{R}} c^k f^c(c) \mathrm{d}c$$

so that  $C_0 = 1$  and  $C_1 = 0$ .

<u>standardized moments</u>: with  $\sigma = \sqrt{C_2}$ ,  $f^s(s) = \frac{\sigma}{\rho}f(u + \sigma s)$ 

$$S_k = \frac{1}{m_0} \int_{\mathbb{R}} \left( \frac{v - u}{\sqrt{C_2}} \right)^k f(v) \mathrm{d}v = \int_{\mathbb{R}} s^k f^s(s) \mathrm{d}s$$

so that  $S_0 = 1$ ,  $S_1 = 0$  and  $S_2 = 1$ .

link:

$$C_{k} = \sum_{i=0}^{k} {\binom{k}{i}} \left(-\frac{m_{1}}{m_{0}}\right)^{k-i} m_{i}, \quad m_{k} = \rho \left(\sum_{i=2}^{k} {\binom{k}{i}} u^{k-i} C_{i} + u^{k}\right), \quad S_{k} = \frac{C_{k}}{(C_{2})^{k/2}}.$$

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# Property of the characteristic polynomial

 $\mathbf{m}_N = (m_0, m_1, \dots, m_N)^t$  be a realizable moment vector such that  $m_0 > 0$  and  $C_2 > 0$ . linear functional  $\langle . \rangle_{\mathbf{m}_N}$  on the space  $\mathbb{R}[X]_N$ 

$$\langle X^k \rangle_{\mathbf{m}_N} = m_k, \quad \text{for } k \in \{0, 1, \dots, N\}.$$

linear functional  $\langle . \rangle_{S_N}$  associated with the standardized moments  $S_N = (S_0, \dots, S_N)^t$ :

$$\langle X^k \rangle := \langle X^k \rangle_{\mathbf{S}_N} = S_k, \text{ for } k \in \{0, 1, \dots, N\}.$$

### Property of the scaled characteristic polynomial

Let us assume that the function  $S_{N+1}$  does not depend on  $(m_0, u, C_2)$ , i.e.,  $S_{N+1}(S_3, \ldots, S_N)$ . Then, the following polynomial

$$P_{N+1}(X) := \overline{P}_{N+1}\left(u + C_2^{1/2}X\right)C_2^{-(N+1)/2}$$

only depends on  $(S_3, \ldots, S_N)$ , and

$$\langle P_{N+1} \rangle = 0, \quad \langle P'_{N+1} \rangle = 0, \quad \langle XP'_{N+1} \rangle = 0.$$

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# QMOM: Principles of the method

From a strictly realizable moment vector  $\mathbf{m}_{2n-1}$ 

Reconstruction  
reconstruct the discret measure 
$$\mu = \sum_{i=1}^{n} w_i \delta_{u_i}$$
  
in such a way that  
 $\sum_{i=1}^{n} w_i u_i^k = m_k \quad k = 0, 1, \dots, 2n-1$ 

### Closure

$$m_{2n} = \int_{\mathbb{R}} \mathbf{v}^{2n} \mathrm{d}\mu = \sum_{i=1}^{n} w_i u_i^{2n}$$

It is the minimal value for this moment

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# QMOM: Principles of the method

From a strictly realizable moment vector  $\mathbf{m}_{2n-1}$ 

# Reconstruction reconstruct the discret measure $\mu = \sum_{i=1}^{n} w_i \delta_{u_i}$ in such a way that $\sum_{i=1}^{n} w_i u_i^k = m_k \quad k = 0, 1, \dots, 2n-1$

### Closure

$$m_{2n} = \int_{\mathbb{R}} v^{2n} \mathrm{d}\mu = \sum_{i=1}^{n} w_i u_i^{2n}$$

It is the minimal value for this moment

From the standardized moments  $\mathbf{S}_{2n-1}$ , with  $\rho = m_0$ ,  $u = m_1/m_0$ ,  $\sigma = \sqrt{C_2}$ 

### Reconstruction

reconstruct the discret measure  

$$\mu = \sum_{i=1}^{n} \rho \omega_i \delta_{u+\sigma c_i} \text{ in such a way that}$$

$$\sum_{i=1}^{n} \omega_i c_i^k = S_k \quad k = 0, 1, \dots, 2n-1$$

### Closure

$$S_{2n} = \sum_{i=1}^n \omega_i c_i^{2n}$$

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# QMOM: Principles of the method

From a strictly realizable moment vector  $\mathbf{m}_{2n-1}$ 

# Reconstructionreconstruct the discret measure $\mu = \sum_{i=1}^{n} w_i \delta_{u_i}$ in such a way that $\sum_{i=1}^{n} w_i u_i^k = m_k \quad k = 0, 1, \dots, 2n-1$ Closure $m_{2n} = \int_{\mathbb{R}} v^{2n} d\mu = \sum_{i=1}^{n} w_i u_i^{2n}$ Closure $m_{2n} = \int_{\mathbb{R}} v^{2n} d\mu = \sum_{i=1}^{n} w_i u_i^{2n}$

It is the minimal value for this moment

$$S_{2n} = \sum_{i=1}^{n} \omega_i c_i^{2n}$$

From the standardized moments  $S_{2n-1}$ ,

with  $\rho = m_0, \, u = m_1/m_0, \, \sigma = \sqrt{C_2}$ 

### Remarks

The reconstruction μ is the only one possible for the moment vector m<sub>2n</sub>.

•  $\mathbf{m}_{2n}$  is at the boundary of the moment space:  $\underline{H}_{2n} = 0$ 

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# QMOM: Computation of the weights and abscissas

m<sub>2n-1</sub>: strictly realizable moment vector

Orthogonal polynomials

Family  $(Q_k)_{k=0,...,n}$  of monic orthogonal polynomials for the scalar product  $(p,q) \mapsto \langle pq \rangle$  of  $\mathbb{R}_n[X]$ .

$$Q_{k+1}(X) = (X - a_k)Q_k(X) - b_kQ_{k-1}(X)$$

with  $Q_{-1} = 0$  and  $Q_0 = 1$ .

The recurrence coefficients  $a_k$  and  $b_k$  can be found from the standardized moments using the Chebyshev algorithm [Chebyshev, 1859, Wheeler, 1974, Gautschi, 2004]

$$a_{k} = \frac{\langle X Q_{k}^{2} \rangle}{\langle Q_{k}^{2} \rangle}, \qquad b_{k} = \frac{\langle Q_{k}^{2} \rangle}{\langle Q_{k-1}^{2} \rangle} = \frac{H_{2k}H_{2k-4}}{H_{2k-2}^{2}}$$

example

$$a_{0} = 0, \qquad a_{1} = S_{3}, \qquad a_{2} = \frac{S_{5} - S_{3}(2 + S_{3}^{2} + 2H_{4})}{H_{4}}$$
  

$$b_{0} = 1, \qquad b_{1} = 1, \qquad b_{2} = H_{4}, \qquad b_{3} = H_{6}/H_{4}^{2}$$
  

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The abscissas  $c_i$  are the zeros of  $Q_n$  and also the eigenvalues of the Jacobi matrix

$$\mathbf{J}_{n} = \begin{pmatrix} a_{0} & \sqrt{b_{1}} & & & \\ \sqrt{b_{1}} & a_{1} & \sqrt{b_{2}} & & \\ & \ddots & \ddots & \ddots & \\ & & \sqrt{b_{n-2}} & a_{n-2} & \sqrt{b_{n-1}} \\ & & & & \sqrt{b_{n-1}} & a_{n-1} \end{pmatrix}$$

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# Hyperbolicity of the QMOM method

### Theorem

The QMOM closure  $b_n = 0$  induces the following characteristic polynomial  $P_{2n} = Q_n^2$  and the system is only weakly hyperbolic.

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proof [Chalons et al., 2012, Huang et al., 2020]

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First version of HyQMOM

# First version of the HyQMOM closure [Fox et al., 2018]

Extension of QMOM, adding one moment and one abscissa for the reconstruction [Fox et al., 2018]

three-node HyQMOM

reconstruction with an additional fixed abscissa  $\mu = w_0 \delta_u + \sum w_i \delta_{u_i}$  in such a way that

$$w_0 u^k + \sum_{i=1}^n w_i u_i^k = m_k \quad k = 0, 1, \dots, 4$$

### Closure

in term of the standardized moments:  $S_5 = S_3(2S_4 - S_3^2)$ 

### Theorem (Hyperbolicity)

Assuming that the vector  $m_4$  is strictly realizable, then system with the three-node HyQMOM closure is hyperbolic.

### Problem

- The generalization to a larger number of moment is not easy
- The eigenvalues of the problem do not tend to the ones of QMOM when  $\underline{H}_4 \rightarrow 0$

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### New HyQMOM closure

# New HyQMOM closure [Fox and Laurent, 2021]

### Idea:

- Instead of looking at a reconstruction or at a closure on S<sub>2n+1</sub>, one looks at a<sub>n</sub>.
- Have a reduced characteristic polynomial on the form

$$P_{2n+1} = Q_n \left[ (X - \alpha_n) Q_n - \beta_n Q_{n-1} \right]$$

such that  $\beta_n$  tends to zero when  $H_{2n} \rightarrow 0$ .

### Theorem

For all n = 1, 2, ...; let the monic polynomial  $P_{2n+1}$  be given by

$$P_{2n+1} = Q_n [(X - \alpha_n)Q_n - \beta_n Q_{n-1}] \qquad \alpha_n, \beta_n \in \mathbb{R}$$

Then, the following statements are equivalent:

(i) 
$$\langle P_{2n+1} \rangle = 0$$
,  $\langle P'_{2n+1} \rangle = 0$  and  $\langle XP'_{2n+1} \rangle = 0$ .  
(ii)  $\alpha_n = a_n = \frac{1}{n} \sum_{k=0}^{n-1} a_k$  and  $\beta_n = \frac{2n+1}{n} b_n$ .

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New HyQMOM closure

# New HyQMOM closure [Fox and Laurent, 2021]

### Theorem

For all n = 1, 2, ..., 9; the scaled characteristic polynomial can be written as

$$P_{2n+1} = Q_n \left[ (X - \alpha_n) Q_n - \beta_n Q_{n-1} \right]$$

if and only if the closure on  $S_{2n+1}$ , defined through the coefficient  $a_n$ , and the coefficients  $\alpha_n$  and  $\beta_n$  are related to the recurrence coefficients  $a_k$  and  $b_k$  by

$$a_n = \alpha_n = \frac{1}{n} \sum_{k=0}^{n-1} a_k, \quad \beta_n = \frac{2n+1}{n} b_n.$$

Proof using formal computation with matlab symbolic: from the  $a_k$  and  $b_k$ , k = 0, ..., n - 1 (with  $a_0 = 0$ ,  $a_1 = 1$ ,  $b_0 = 1$ )

• set the closure 
$$a_n = \frac{1}{n} \sum_{k=0}^{n-1} a_k$$

compute the Standardized moments S<sub>2n+1</sub> with the reverse Chebyshev algorithm
compute the coefficients c<sub>k</sub> of P<sub>2n+1</sub>
compute the polynomials Q<sub>k</sub>, k = 0, 1, ..., n
compute P<sub>2n+1</sub> - Q<sub>n</sub> [(X - a<sub>n</sub>)Q<sub>n</sub> - <sup>2n+1</sup>/<sub>n</sub> b<sub>n</sub>Q<sub>n-1</sub>]

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$$a_n = \alpha_n = \frac{1}{n} \sum_{k=0}^{n-1} a_k, \quad \beta_n = \frac{2n+1}{n} b_n.$$

### Examples

- n = 1:  $S_3 = 0$  (as for the Maxwellian reconstruction)
- n = 2:  $S_5 = \frac{1}{2}S_3(5S_4 3S_3^2 1)$  (different from the previous version:  $S_5 = S_3(2S_4 - S_3^2)$ )

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# Hyperbolicity - Eigenvalues

### Theorem

When  $\beta_n > 0$ , the n + 1 roots of  $R_{n+1} = (X - \alpha_n)Q_n - \beta_nQ_{n-1}$  are real-valued and bound and separate the n roots of  $Q_n$ .

comes from Christoffel-Darboux formula.

The roots of  $P_{2n+1}$  are then the eigenvalues of the two following Jacobi matrices:

$$\begin{pmatrix} a_0 & \sqrt{b_1} & & & \\ \sqrt{b_1} & a_1 & \sqrt{b_2} & & \\ & \ddots & \ddots & & \\ & & \sqrt{b_{n-2}} & a_{n-2} & \sqrt{b_{n-1}} \\ & & & & \sqrt{b_{n-1}} & a_{n-1} \end{pmatrix}, \begin{pmatrix} a_0 & \sqrt{b_1} & & & \\ \sqrt{b_1} & a_1 & \sqrt{b_2} & & \\ & \ddots & \ddots & \ddots & \\ & & & \sqrt{b_{n-1}} & a_{n-1} & \sqrt{\beta_n} \\ & & & & \sqrt{\beta_n} & \alpha_n \end{pmatrix}$$

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# Hyperbolicity - Eigenvalues

### Theorem

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# Hyperbolicity - Eigenvalues

### Theorem

When  $\beta_n > 0$ , the n + 1 roots of  $R_{n+1} = (X - \alpha_n)Q_n - \beta_nQ_{n-1}$  are real-valued and bound and separate the n roots of  $Q_n$ .

comes from Christoffel–Darboux formula.



The moment system with the HyQMOM closure is then hyperbolic, whatever the strictly realizable moment.

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# Practical computations

### Closure, directly from the moments $\mathbf{m}_{2n}$

O compute the  $(\bar{a}_k)_{k=0}^{n-1}$  and  $(\bar{b}_k)_{k=0}^n$  from  $\mathbf{m}_{2n}$  with the Chebyshev algorithm

set the closure 
$$\bar{a}_n = \frac{1}{n} \sum_{k=0}^{n-1} \bar{a}_k$$

Compute m<sub>2n+1</sub> using the reverse Chebyshev algorithm



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# Practical computations

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Compute m<sub>2n+1</sub> using the reverse Chebyshev algorithm

### Eigenvalues of the system

eigenvalues of the two following Jacobi matrices:

$$\begin{pmatrix} \bar{a}_0 & \sqrt{\bar{b}_1} & & & \\ \sqrt{\bar{b}_1} & \bar{a}_1 & \sqrt{\bar{b}_2} & & & \\ & \ddots & \ddots & \ddots & & \\ & & \sqrt{\bar{b}_{n-2}} & \bar{a}_{n-2} & \sqrt{\bar{b}_{n-1}} \\ & & & & \sqrt{\bar{b}_{n-1}} & \bar{a}_{n-1} \end{pmatrix}, \quad \begin{pmatrix} \bar{a}_0 & \sqrt{\bar{b}_1} & & & \\ \sqrt{\bar{b}_1} & \bar{a}_1 & \sqrt{\bar{b}_2} & & & \\ & \ddots & \ddots & \ddots & & \\ & & & \sqrt{\bar{b}_{n-1}} & \bar{a}_{n-1} & \sqrt{\frac{2n+1}{n}\bar{b}_n} \\ & & & & \sqrt{2n+1}\bar{b}_n & \bar{a}_n \end{pmatrix}$$

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# Practical computations

### Closure, directly from the moments $\mathbf{m}_{2n}$

**(**) compute the  $(\bar{a}_k)_{k=0}^{n-1}$  and  $(\bar{b}_k)_{k=0}^n$  from  $\mathbf{m}_{2n}$  with the Chebyshev algorithm

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### Reconstruction

A reconstruction as a sum of weighted Dirac delta function corresponds to the closure. The abscissas and weights can be easily computed from the  $(\bar{a}_k, \bar{b}_k)_{k=0,...,n}$ .

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- Principle of the method
- Hyperbolicity
- - First version of HyQMOM
  - New HyQMOM closure
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Configuration

# The 1D Riemann problem

### problem at the kinetic level

Two homogeneous sprays, with Gaussian distribution and infinite Stokes, crossing.

Problem at the kinetic level

$$\partial_t f + \partial_x (v f) = 0,$$
  
 $f(v; 0, x) = \mathcal{M}_\sigma (v - \overline{u}(x))$ 

with 
$$\sigma = 1/3$$
  
 $\bar{u}(x) = \begin{cases} 1 & \text{if } x < 0, \\ -1 & \text{otherwise.} \end{cases}$   
Analytical solution  $f(t, x, v) = \mathcal{M}_{\sigma}(v - \bar{u}(x - vt)) = \begin{cases} \mathcal{M}_{\sigma}(v - 1) & \text{if } v > x/t, \\ \mathcal{M}_{\sigma}(v + 1) & \text{otherwise.} \end{cases}$ 



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### moment problem

$$\partial_t m_k + \partial_x m_{k+1} = 0, \quad k = 0, \ldots, 2n$$

with the initial condition for the standardized moments

$$\rho(0, x) = 1, \quad u(0, x) = \bar{u}(x), \quad C_2(0, x) = \sigma, \quad \begin{cases} S_{2k-1} = 0, \\ S_{2k} = (2k-1)S_{2k-2}, \end{cases} \quad k = 2, \dots, r$$
  
numerical scheme: HLL [Harten et al., 1983]

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# The 1D Riemann problem - Results

moments - cases n=2,3,4



Good behavior on this hard test case.

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# The 1D Riemann problem - Results

standardized moments - cases n=2,3,4



Good behavior on this hard test case.

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# The 1D Riemann problem - Results

first moments - case n=10



Close to the analytical solution.

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# The 1D Riemann problem - Results

first standardized moments - case n=10



Close to the analytical solution.

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# The 1D Riemann problem - Convergence

error on the moments



The moment method seems to converge to the solution of the kinetic equation when the number of moments increases.

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# **Conclusion and Perspectives**

### Conclusion

- Closure inducing a global hyperbolicity
- Include the Maxwellian distribution
- Good behavior at the boundary of the moment space
- Efficient algorithm to compute the closure and the eigenvalues

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# **Conclusion and Perspectives**

### Conclusion

- Closure inducing a global hyperbolicity
- Include the Maxwellian distribution
- Good behavior at the boundary of the moment space
- Efficient algorithm to compute the closure and the eigenvalues

### Perspectives

2D-3D version of the HyQMOM closure

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# **Conclusion and Perspectives**

### Conclusion

- Closure inducing a global hyperbolicity
- Include the Maxwellian distribution
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### Perspectives

2D-3D version of the HyQMOM closure

# THANK YOU FOR YOUR ATTENTION

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# Chebyshev algorithm

<u>Three terms recurrence relation</u> for a sequence  $(Q_k)_{k\geq 0}$  of orthogonal polynomials relative to  $\langle ., . \rangle$ :

$$Q_{k+1}(x) = (x - a_k)Q_k(x) - b_kQ_{k-1}(x).$$

Chebyshev algorithm [Chebyshev, 1859, Wheeler, 1974, Gautschi, 2004]  $Z_{k,p} = \langle Q_k X^p \rangle$   $Z_{-1,p} = 0, \quad Z_{0,p} = m_p$   $Z_{k+1,p} = Z_{k,p+1} - a_k Z_{k,p} - b_k Z_{k-1,p}.$  $b_0 = m_0, \quad a_0 = \frac{m_1}{m_0}, \quad \forall k > 0 \quad b_k = \frac{Z_{k,k}}{Z_{k-1,k-1}}, \quad a_k = \frac{Z_{k,k+1}}{Z_{k,k}} - \frac{Z_{k-1,k}}{Z_{k-1,k-1}},$ 

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