

A multigrid solver for the M_1 model for radiative transfer

Hélène BLOCH

Pascal TREMBLIN (Maison de la Simulation)

Edouard AUDIT (Maison de la Simulation)

Matthias GONZÁLEZ (AIM)

10 ième Biennale Française des Mathématiques Appliquées et Industrielles

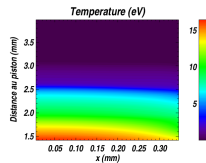


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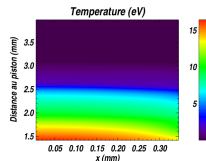
Many physical situations



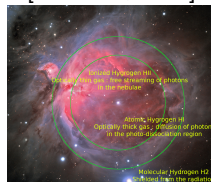
[González, 2006]

Many physical situations

- Laser-matter interactions

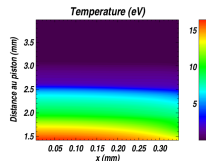


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Many physical situations

- Laser-matter interactions
- Astrophysics: HII region, ...



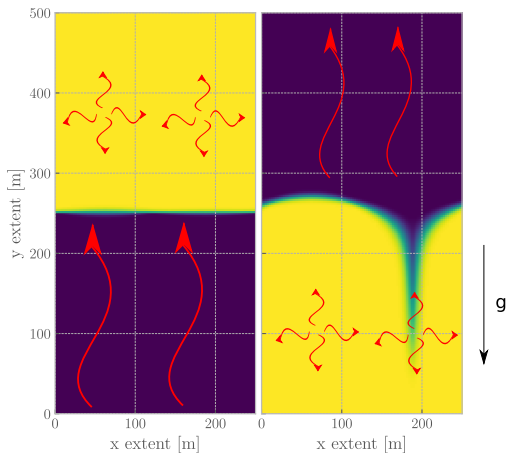
[González, 2006]



[Tremblin et al., prep]

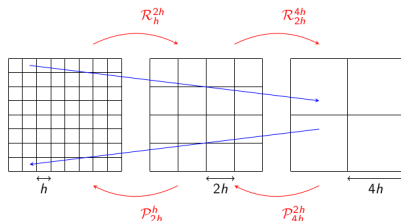
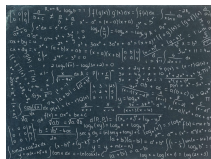
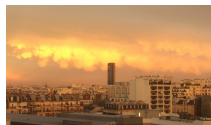
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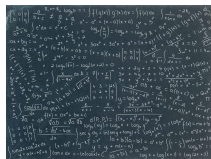
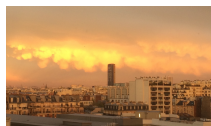
- Laser-matter interactions
- Astrophysics: HII region, ...
- Atmospheric physics



[Tremblin et al., prep] : opacity jump interface

- 1 M_1 model
- 2 A geometric multigrid solver
- 3 Conclusion

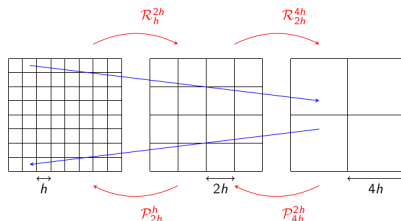




1 M₁ model

2 A geometric multigrid solver

3 Conclusion





Moment method

- Grey radiative transfer equation without scattering ¹

$$\left(\frac{1}{c} \partial_t + \mathbf{n} \cdot \nabla \right) I(\mathbf{x}, t, \mathbf{n}) = \sigma B(\mathbf{x}, t) - \sigma I(\mathbf{x}, t, \mathbf{n})$$

¹[Mihalas and Mihalas, 1984]



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- First moments of the specific intensity:
 - E_r radiative energy
 - $\mathbf{F}_r$ radiative flux
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$$\partial_t E_r + \nabla \cdot \mathbf{F}_r = c\sigma(a_r T_g^4 - E_r)$$

$$\partial_t \mathbf{F}_r + c^2 \nabla \cdot \mathbb{P}_r = -c\sigma \mathbf{F}_r$$

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- Admissible states: $E_r > 0$ and $\frac{\|\mathbf{F}_r\|}{cE_r} \leq 1$

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Closure relation

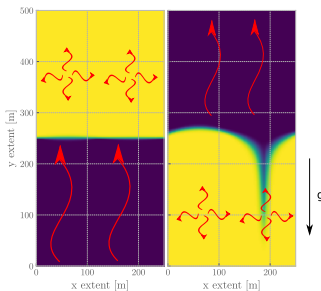
M₁ model closure relation ²

$$\mathbb{P}_r = \mathbb{D} E_r$$

where $\mathbb{D}$ is the Eddington tensor

$$\mathbb{D} = \frac{1 - \chi}{2} \mathbb{I} + \frac{3\chi - 1}{2} \mathbf{n} \otimes \mathbf{n}$$

- Free-streaming regime:
 $\chi(E_r, \mathbf{F}_r) = 1, \mathbb{D} = \mathbf{n} \otimes \mathbf{n}$
- Diffusive limit:
 $\chi(E_r, \mathbf{F}_r) = \frac{1}{3}, \mathbb{D} = \frac{1}{3} \mathbb{I}$



²[Dubroca and Feugeas, 1999]



Numerical scheme

- Implicit



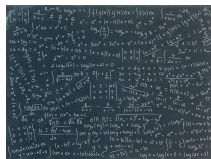
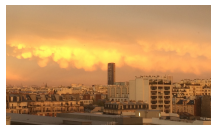
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Numerical scheme

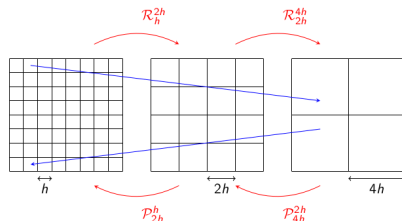
- Implicit
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- Source terms



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Implicit solver

- Speed of light
 $c = 3 \times 10^5 \text{ km s}^{-1}$
- Speed of sound
 $v = 10 \text{ km s}^{-1}$
- $\frac{c}{v} = 3 \times 10^4$
- Implicit scheme with time step
 $\Delta t = 3 \times 10^4 \frac{h}{c}$





Newton method

- Compute the Jacobian



Newton method

- Compute the Jacobian
- Solve linear system



Newton method

- Compute the Jacobian
- Solve linear system
- Does not preserve the admissible states $E_r > 0$ and $\frac{\|\mathbf{F}_r\|}{cE_r} \leq 1$



Jacobi method

$$\begin{aligned} E_i^{n+1} \left(1 + c \frac{\Delta t}{h} \right) &= E_i^n \\ &+ \frac{\Delta t}{2h} (cE_{i+1}^{n+1} - F_{i+1}^{n+1}) + \frac{\Delta t}{2h} (cE_{i-1}^{n+1} + F_{i-1}^{n+1}) \\ F_i^{n+1} \left(1 + c \frac{\Delta t}{h} \right) &= F_i^n \\ &+ \frac{c\Delta t}{2h} (F_{i+1}^{n+1} - cP_{i+1}^{n+1}) + \frac{c\Delta t}{2h} (F_{i-1}^{n+1} + cP_{i-1}^{n+1}) \end{aligned}$$

[Pichard, 2016]



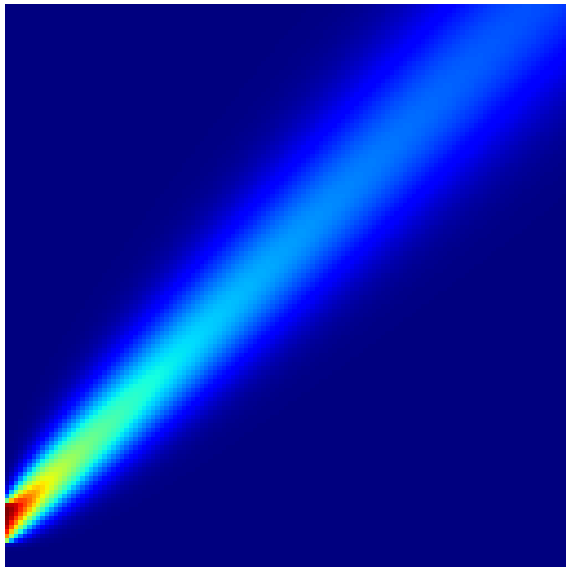
Jacobi method

$$\begin{aligned}
 E_i^{n+1,k+1} \left(1 + c \frac{\Delta t}{h} \right) &= E_i^n \\
 &+ \frac{\Delta t}{2h} \left(cE_{i+1}^{n+1,k} - F_{i+1}^{n+1,k} \right) + \frac{\Delta t}{2h} \left(cE_{i-1}^{n+1,k} + F_{i-1}^{n+1,k} \right) \\
 F_i^{n+1,k+1} \left(1 + c \frac{\Delta t}{h} \right) &= F_i^n \\
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 \end{aligned}$$

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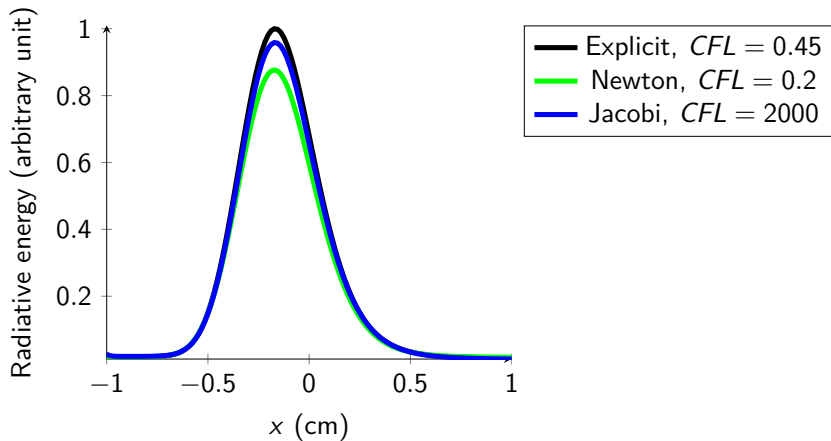


Beam test



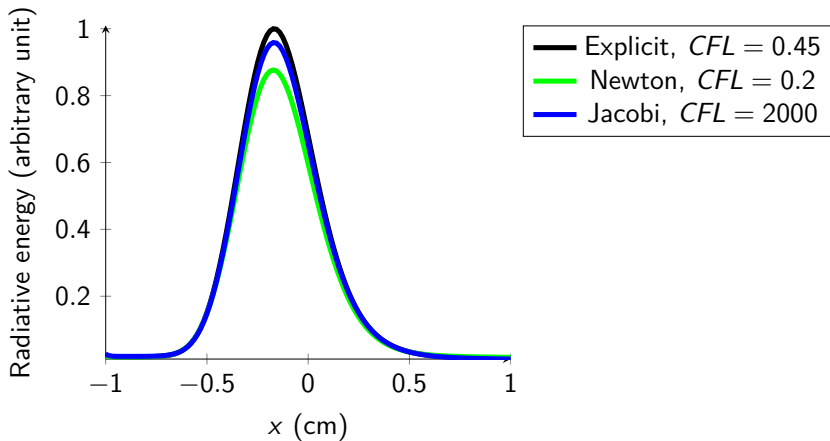


Beam test





Beam test



Jacobi three times faster than explicit solver

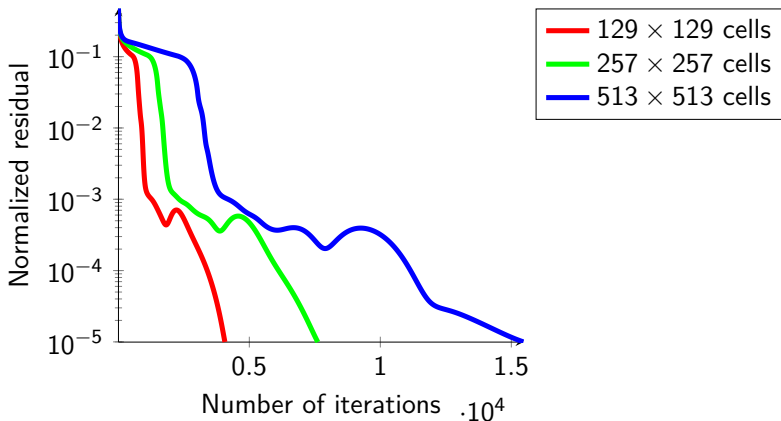


Convergence

$$v_i = (E_i, F_i)$$

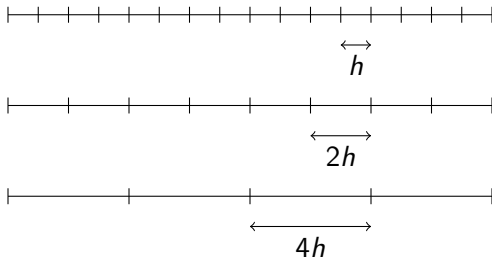
$$\text{Solve } \mathcal{A}(\mathbf{v}) = \mathbf{f}$$

$$\text{Residual: } \|\mathbf{f} - \mathcal{A}(\mathbf{v})\|$$





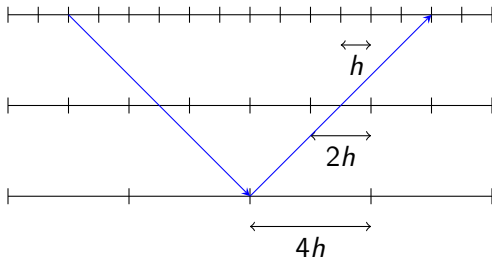
Geometric multigrid (GMG)



[Briggs et al., 2000]



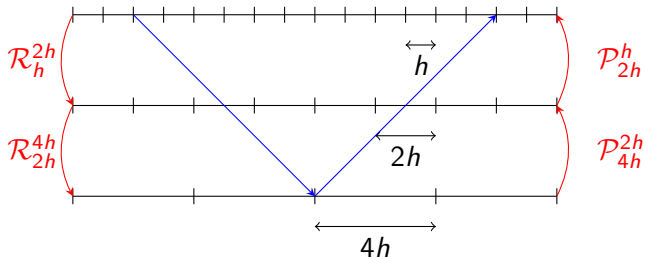
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Full Approximation Scheme (FAS)

- Pre-smoother: relax a few times $\mathcal{A}^h(\mathbf{v}^h) = \mathbf{f}^h$.

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- Post-smoother: relax a few times $\mathcal{A}^h(\mathbf{v}^h) = \mathbf{f}^h$.

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Admissible states

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Pseudo-time equation

Instead of solving

$$\mathcal{A}^{2h}(\mathbf{u}^{2h}) = \mathbf{r}^{2h} + \mathcal{A}^{2h}(\mathbf{v}^{2h}),$$

[Kifonidis and Müller, 2012]



Pseudo-time equation

Instead of solving

$$\mathcal{A}^{2h}(\mathbf{u}^{2h}) = \mathbf{r}^{2h} + \mathcal{A}^{2h}(\mathbf{v}^{2h}),$$

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$$\frac{d\mathbf{u}^{2h}}{d\tau} + \mathcal{A}^{2h}(\mathbf{u}^{2h}) = \mathbf{r}^{2h} + \mathcal{A}^{2h}(\mathbf{v}^{2h}),$$

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as

$$\begin{aligned} \frac{\widetilde{\mathbf{u}}^{2h} - (\mathbf{u}^{2h})^m}{\Delta\tau} &= \mathbf{r}^{2h} + \mathcal{A}^{2h}(\mathbf{v}^{2h}) \\ \frac{(\mathbf{u}^{2h})^{m+1} - \widetilde{\mathbf{u}}^{2h}}{\Delta\tau} + \mathcal{A}^{2h}\left((\mathbf{u}^{2h})^{m+1}\right) &= 0 \end{aligned}$$

[Kifonidis and Müller, 2012]



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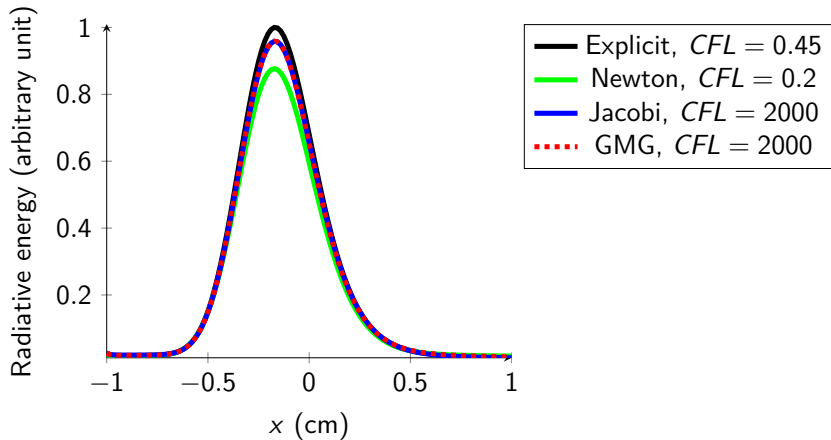
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$$\begin{aligned}\widetilde{\mathbf{u}}^{2h} &= \left(\mathbf{u}^{2h}\right)^m + \Delta\tau \left(\mathbf{r}^{2h} + \mathcal{A}^{2h}(\mathbf{v}^{2h})\right) \\ \left(\mathbf{u}^{2h}\right)^{m+1} + \Delta\tau \mathcal{A}^{2h} \left(\left(\mathbf{u}^{2h}\right)^{m+1}\right) &= \widetilde{\mathbf{u}}^{2h}\end{aligned}$$

[Kifonidis and Müller, 2012]

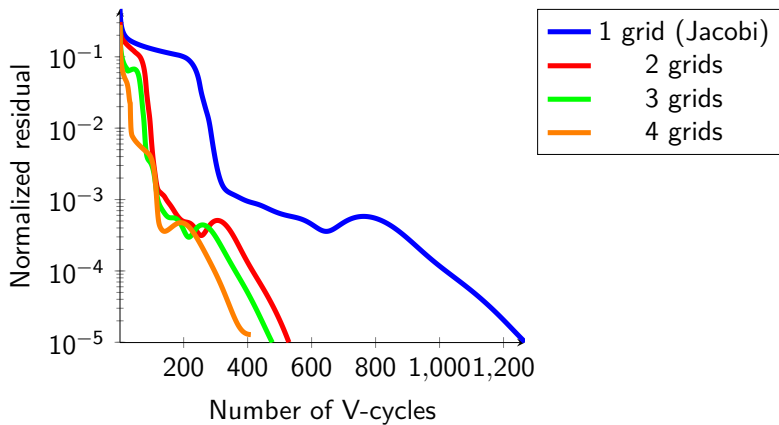


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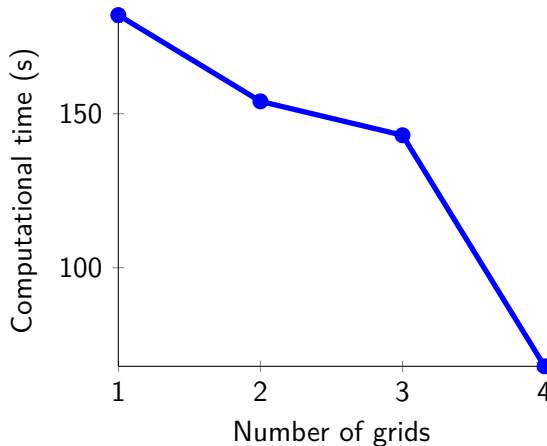


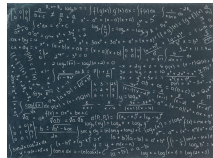
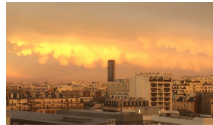
Convergence





Computational time

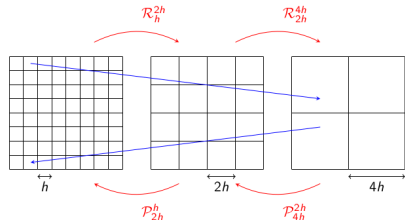




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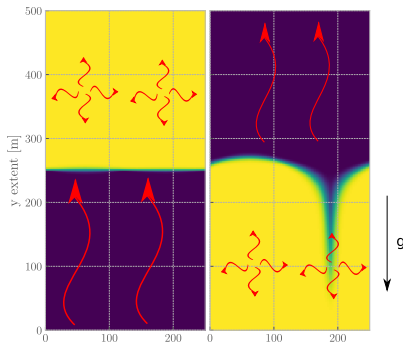
3 Conclusion





Conclusion and perspectives

- Conclusion
 - Implicit scheme with Jacobi method
 - Geometric multigrid
- Perspectives
 - Source terms
 - Coupling to hydrodynamics for physical applications





Prolongation operator

$$\left(\mathcal{P}_{2h}^h(\mathbf{v}^{2h})\right)_{i^h,j^h} = \begin{cases} \mathbf{v}_{i^{2h},j^{2h}}^{2h} & \text{if } i^h \text{ is even and } j^h \text{ is even,} \\ \frac{1}{2} \left(\mathbf{v}_{i^{2h},j^{2h}}^{2h} + \mathbf{v}_{i^{2h}+1,j^{2h}}^{2h} \right) & \text{if } i^h \text{ is odd and } j^h \text{ is even,} \\ \frac{1}{2} \left(\mathbf{v}_{i^{2h},j^{2h}}^{2h} + \mathbf{v}_{i^{2h},j^{2h}+1}^{2h} \right) & \text{if } i^h \text{ is even and } j^h \text{ is odd,} \\ \frac{1}{4} \left(\mathbf{v}_{i^{2h},j^{2h}}^{2h} + \mathbf{v}_{i+1^{2h},j^{2h}}^{2h} + \mathbf{v}_{i^{2h},j^{2h}+1}^{2h} + \mathbf{v}_{i+1^{2h},j^{2h}+1}^{2h} \right) & \text{if } i^{2h} \text{ is odd and } j^{2h} \text{ is odd.} \end{cases}$$

[Strang, 2006]



Restriction operator

$$\begin{aligned} \left(\mathcal{R}_h^{2h} \left(\mathbf{v}^h \right) \right)_{i^{2h}, j^{2h}} &= \frac{1}{16} \mathbf{v}_{i^h-1, j^h-1}^h + \frac{1}{8} \mathbf{v}_{i^h-1, j^h}^h + \frac{1}{16} \mathbf{v}_{i^h-1, j^h+1}^h \\ &+ \frac{1}{8} \mathbf{v}_{i^h, j^h-1}^h + \frac{1}{4} \mathbf{v}_{i^h, j^h}^h + \frac{1}{8} \mathbf{v}_{i^h, j^h+1}^h \\ &+ \frac{1}{16} \mathbf{v}_{i^h+1, j^h-1}^h + \frac{1}{8} \mathbf{v}_{i^h+1, j^h}^h + \frac{1}{16} \mathbf{v}_{i^h+1, j^h+1}^h. \end{aligned}$$

[Strang, 2006]



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Dubroca, B. and Feugeas, J.-L. (1999).

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