Classifying histograms using information geometry of beta distributions

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A. L., N. Guigui, S. Rebbah, S. Puechmorel,

Classifying histograms of medical data using information geometry of beta distributions.

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A. L., S. Preston, S. Puechmorel, Fisher-Rao geometry of Dirichlet distributions. *Differential Geometry and its Applications* 74 (2021) : 101702.

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Non Euclidean data

Statistics have been developed for Euclidean data

$$x_1,\ldots,x_n\in\mathbb{R}^d,\quad \bar{x}=\frac{1}{n}\sum_{i=1}^n x_i$$

In many applications, the data of interest do not belong to a vector space

- Geostatistics \rightarrow spherical data
- Diffusion tensor images \rightarrow SPD matrices
- Character animations \rightarrow rotation matrices
- Images \rightarrow histograms, probability distributions
- Shapes of curves, surfaces \rightarrow immersions, submanifolds







Fletcher et al. 2004

Fletcher et al. 2006

Celledoni et al. 2016

Alice Le Brigant

Classifying histograms with information geometry

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All these objects can be seen as elements of differentiable manifolds

- Open sets of vector spaces (SPD matrices, immersions)
- Embedded submanifolds (sphere)

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To do statistics on these objects, one can use Riemannian geometry.

- Euclidean scalar product \rightarrow Riemannian metric
- straight lines \rightarrow geodesics
- Euclidean distance \rightarrow geodesic distance
- addition / subtraction \rightarrow Riemannian exponential / logarithm



Riemannian geometry is a convenient framework to generalize usual statistical notions and data processing algorithms.

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Example : the **Fréchet mean**
$$x_m = \underset{y \in M}{\operatorname{argmin}} \frac{1}{n} \sum_{i=1}^n d(x_i, y)^2.$$

- In general, it is not unique
- Unicity under certain conditions on injectivity radius of the data manifold
- Or for Hadamard manifolds (geodesically complete and negative curvature)
- In a Riemannian manifold, it can be computed via a gradient descent based on the Riemannian Logarithm

$$F(\mathbf{y}) = \frac{1}{n} \sum_{i=1}^{n} d(x_i, \mathbf{y})^2, \qquad \nabla_{\mathbf{y}} F \propto -\sum_{i=1}^{n} \log_{\mathbf{y}}(x_i).$$

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Knowledge of the **data manifold geometry** (existence of geodesics, curvature...) is important to apply geometric statistics on it.

Histogram data

Here we focus on histogram data.



- Each data point is a histogram of bounded values, e.g. measurements corresponding to a patient
- Lack of a common representation space : a correspondence between measurements across patients may not exist
- Bounded values : a beta distribution is fitted to each histogram
- Idea : do geometric statistics on dataset of beta distributions

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- 4 Generalization to Dirichlet distributions

 Information geometry : geometric approach to parametric statistics based on the Fisher information. Given a parametric model {p_θμ, θ ∈ Θ},

$$I(\mathbf{\theta}) = \mathbb{E}_{\mathbf{\theta}}[\partial_{\mathbf{\theta}}\ell_{\mathbf{\theta}}(X) \cdot \partial_{\mathbf{\theta}}\ell_{\mathbf{\theta}}(X)^{t}], \quad \ell_{\mathbf{\theta}} = \log p_{\mathbf{\theta}}.$$

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 Rao (1945) : the Fisher information can be used to define a Riemannian metric on the parameter space Θ, i.e. a local scalar product on each tangent space

$$\langle u,v\rangle_{\boldsymbol{\theta}} = {}^{t} u I(\boldsymbol{\theta})v, \quad u,v \in T_{\boldsymbol{\theta}} \boldsymbol{\Theta} \simeq \mathbb{R}^{d}.$$

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• The induced geodesic distance is called the Fisher-Rao distance

$$\operatorname{dist}(\theta_0, \theta_1) = \inf_{\theta(0) = \theta_0, \theta(1) = \theta_1} \ell(\theta) \quad \text{where} \quad \ell(\theta) = \int_0^1 \|\theta'(t)\|_{\theta(t)} dt.$$

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- The Fisher-Rao metric is invariant to
 - diffeomorphic parametrization change $\phi: \theta \mapsto \tilde{\theta}$.
 - transformation of the statistical model by a sufficient statistic (Chentsov).

• **Geodesics** are local minimizers of the geodesic distance and curves $t \mapsto \gamma(t)$ with zero acceleration

$$\nabla_{\dot{\gamma}}\dot{\gamma}=0$$

where ∇ is the *Levi-Civita connection* and allows to take "intrinsic" derivatives of vector fields \rightarrow geodesics are **solutions of an ODE**.

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• If the manifold has **negative curvature** and is simply connected, the minimizing geodesic is unique (Cartan-Hadamard theorem).

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Examples

• Univariate normal distributions (Atkinson & Mitchell 1981) $p_{\theta} = \mathcal{N}(\mu, \sigma)$, then $\Theta = \mathbb{R} \times \mathbb{R}^*_+$ equipped with the Fisher-Rao metric is the Poincaré half-plane. Geodesics are half-circles orthogonal to the *x*-axis.



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Poincaré half-plane. Geodesics are half-circles orthogonal to the *x*-axis.



- Others :
 - Special cases of multivariate normal distributions (Atkinson & Mitchell 1981, Skovgaard 1984)
 - Gamma distributions (Lauritzen 1987, Arwini & Dodsen 2008)
 - Power inverse Gaussian distributions (Zhang, Sun, Zhong, 2007)
 - Von Mises-Fisher and location-scale models (Said et al. 2019)
 - Generalized Gamma distributions (Rebbah, Nicol, Puechmorel 2019)

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- Parameter space is $\Theta = \{(x, y), x > 0, y > 0\}.$
- The beta p.d.f. of parameter $\theta\in\Theta$ is

$$p_{\boldsymbol{\theta}}(u) = \frac{\Gamma(x+y)}{\Gamma(x)\Gamma(y)} u^{x-1} (1-u)^{y-1}, \quad \forall u \in [0,1].$$



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• The Fisher-Rao metric is defined for any $v = (v_x, v_y) \in T_{(x,y)}\Theta$ by

$$\|v\|^{2} = \psi'(x)v_{x}^{2} + \psi'(y)v_{y}^{2} - \psi'(x+y)(v_{x}+v_{y})^{2},$$

where $\psi = \Gamma' / \Gamma$ and ψ' are the digamma and trigamma functions.

• Parameter space Θ + Fisher-Rao metric = **beta manifold**.

• The geodesics $t \mapsto (x(t), y(t))$ can be found numerically by solving the ODE

$$\ddot{x} + a(x,y)\dot{x}^2 + b(x,y)\dot{x}\dot{y} + c(x,y)\dot{y}^2 = 0$$

$$\ddot{y} + a(y,x)\dot{y}^2 + b(y,x)\dot{x}\dot{y} + c(y,x)\dot{x}^2 = 0$$

with

$$\begin{split} a(x,y) &= \frac{\psi''(x)\psi'(y) - \psi''(x)\psi'(x+y) - \psi'(y)\psi''(x+y)}{2d(x,y)},\\ b(x,y) &= -\frac{\psi''(x+y)\psi'(y)}{d(x,y)},\\ c(x,y) &= \frac{\psi''(y)\psi'(x+y) - \psi'(y)\psi''(x+y)}{2d(x,y)},\\ d(x,y) &= \psi'(x)\psi'(y) - \psi'(x+y)(\psi'(x) + \psi'(y)). \end{split}$$

Initial value problem : fix x(0), y(0), x(0), y(0)
 Boundary value problem : fix x(0), y(0), x(1), y(1).



	Euclidean	Fisher-Rao
dist((1,10),(10,1))	12,7	4,2
dist((1,10),(10,100))	99,4	1,8

Computation of geodesics allows to compute

- distances
- interpolations
- barycenters

Questions :

- Are the geodesics always defined? Unique?
- What is the curvature of the beta manifold?





Gauss curvature of a surface $S \subset \mathbb{R}^3$

- The normal to *S* defines the *Gauss map* $N: S \to \mathbb{R}^3$.
- The shape operator $\Sigma_p(v) = -dN_p(v)$ is symmetric and defines the second fundamental form

$$\mathrm{II}_p(v) = \langle \Sigma_p(v), v \rangle.$$

It is the signed curvature of the normal section of S at p in direction v.

- The principal curvatures k₁ and k₂ are the extremal eigenvalues of the shape operator Σ_p
- Mean (extrinsic) curvature : $\frac{k_1+k_2}{2}$ vs Gauss (intrinsic) curvature : k_1k_2



Sectional curvature of a Riemannian manifold M

Sectional curvature of a plane σ ⊂ T_pM spanned by vectors e₁, e₂

$$K(\mathbf{\sigma}) = K(e_1, e_2) = \frac{\langle R(e_1, e_2)e_1, e_2 \rangle}{\langle e_1, e_1 \rangle \langle e_2, e_2 \rangle - \langle e_1, e_2 \rangle^2}$$

where $R(U, V)W = \nabla_U \nabla_V W - \nabla_V \nabla_U W - \nabla_{[U,V]} W$ is the curvature tensor.

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• When M is a **hypersurface** in \overline{M} , then the Gauss map $p \mapsto N(p)$ is defined and

$$K(U,V) - \bar{K}(U,V) = \frac{\langle \Sigma(U), U \rangle \langle \Sigma(V), V \rangle - \langle \Sigma(U), V \rangle^2}{\langle U, U \rangle \langle V, V \rangle - \langle U, V \rangle^2}.$$

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If *K* = 0 and for an o.n.b. of eigenvectors *e*₁,...,*e_n* of Σ_p associated to the eigenvalues *k*₁,...,*k_n* (*principal curvatures*), we get

$$K(e_i, e_j) = k_i k_j.$$

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- Only one sectional curvature $K(\theta)$ at each point $\theta = (x, y)$ (dim = 2)
- At point (x, y), the sectional curvature can be computed from coordinate vectors e_x, e_y:

$$K(x,y) = \frac{\Psi''(x)\Psi''(y)\Psi''(x+y)}{4d(x,y)^2} \left(\frac{\Psi'(x)}{\Psi''(x)} + \frac{\Psi'(y)}{\Psi''(y)} - \frac{\Psi'(x+y)}{\Psi''(x+y)}\right)$$

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Theorem

The beta manifold has everywhere negative sectional curvature.

• Conjecture : $K \ge -1/2$



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- One can show that the beta manifold is complete, and simply connected, so it is a **Hadamard manifold**
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 - \rightarrow existence and unicity of the Fréchet mean.

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- One can show that the beta manifold is complete, and simply connected, so it is a **Hadamard manifold**
 - \rightarrow existence and unicity of minimizing geodesics
 - \rightarrow existence and unicity of the Fréchet mean.
- Algorithms based on distance and barycenter computations are well defined on the beta manifold.

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Information geometry of beta distributions

Classifying histograms of medical data



Histograms of medical data

Example 1 : Area strain (AS) of the right ventricle

- Goal : observe local stretching of the area of the right ventricle (RV) to assess cardiac function
- Data : area change of each triangular cell of a 3d mesh of the RV
- This gives a distribution of n values in [p,q] with constants p,q.
- Renormalize to obtain values in [0,1].

Example 2 : Cortical thickness (CTh) maps

- Goal : measure brain atrophy for the early diagnosis of Alzheimer's disease
- Data : *n* cortical thickness (CTh) MRI measures along the whole cortical ribbon
- Each measure is made for a 1mm voxel
- Normalize values by maximal value among population

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Methodology

- Each dataset is divided in 2 classes : diseased and controls.
- 1 patient \leftrightarrow 1 histogram \leftrightarrow beta parameters (x, y)
- We perform both supervised (KNN, supervised Kmeans) and unsupervised (Kmeans) classification in the following representation spaces :
 - beta parameter space + Fisher-Rao metric
 - beta parameter space + Euclidean metric
 - original data space + Euclidean metric (only for AS)
 - 2-dimensional space obtained by PCA + Euclidean metric (only for AS)



Results

CTh data



Mean accuracy of KNN on 5-fold cross-validation

	Beta		
	Euclidean	Riemannian	
KNN	0.77 (0.05)	0.79 (0.04)	
SKM	0.66 (0.10)	0.80 (0.05)	
KM	0.61	0.82	

Classification mean (and standard deviation) accuracy on 5-fold cross-validation

Results

AS data



Mean accuracy of KNN on 5-fold cross-validation

	Original	PCA	Beta	
	Euclidean	Euclidean	Euclidean	Riemannian
KNN	0.81 (0.05)	0.67 (0.32)	0.77 (0.09)	0.83 (0.05)
SKM	0.85 (0.03)	0.72 (0.28)	0.66 (0.06)	0.81 (0.06)
KM	0.84	0.84	0.60	0.80

Classification mean (and standard deviation) accuracy on 5-fold cross-validation

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Information geometry of beta distributions





Generalization to Dirichlet distributions

Dirichlet distributions

■ Dirichlet distributions are probability distributions on the (*n*−1)-dimensional probability simplex

$$\Delta_n = \{q = (q_1, \dots, q_n) \in \mathbb{R}^n, \sum_{i=1}^n q_i = 1, q_i \ge 0, i = 1, \dots, n\}.$$

• Parameter space is $\Theta = \{(x_1, \dots, x_n), x_1, \dots, x_n > 0\}$ and p.d.f. is

$$f_n(q|x_1,\ldots,x_n)=\frac{\Gamma(x_1+\ldots+x_n)}{\Gamma(x_1)\ldots\Gamma(x_n)}q_1^{x_1-1}\ldots q_n^{x_n-1}.$$



The Dirichlet manifold

• Notations :
$$f = \frac{1}{\psi'}, F = \frac{\psi'}{\psi''}.$$

• The **Dirichlet manifold** is $\Theta = (\mathbb{R}^*_+)^n$ equipped with the Fisher-Rao metric

$$ds^{2} = \frac{dx_{1}^{2}}{f(x_{1})} + \dots + \frac{dx_{n}^{2}}{f(x_{n})} - \frac{(dx_{1} + \dots + dx_{n})^{2}}{f(x_{1} + \dots + x_{n})}$$

• The sectional curvature of the plane spanned by coordinate vectors *e_i*, *e_j* is

$$K_{ij}(x) = \frac{F(x_i)F(x_j)F(\sum x_k)}{4(f(\sum x_k) - \sum f(x_k))^2} \left(F(x_i) + F(x_j) - F(\sum x_k)\right)$$

 $F \leq 0$ is subadditive $\Rightarrow K_{ij} \leq 0$ everywhere.

• But in dimension *n* > 2, there are other sectional curvatures to consider !

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The Dirichlet manifold

There is an isometric embedding

$$\Phi: M \to L^{n+1},$$

 $(x_1, \dots, x_n) \mapsto (\eta(x_1), \dots, \eta(x_n), \eta(x_1 + \dots + x_n))$
 $\eta: \mathbb{R}_+ \to \mathbb{R}, \quad \eta(x) = \int_1^x \frac{dr}{\sqrt{f(r)}}$

between M and the (n+1)-dimensional flat Minkowski space $L^{n+1} = (\mathbb{R}^{n+1}, ds_L^2)$, where

$$ds_L^2 = dy_1^2 + \ldots + dy_n^2 - dy_{n+1}^2.$$

Proposition

with

 $S = \Phi(M)$ is a codimension 1 submanifold (hypersurface) of L^{n+1} given by the graph of

$$y_{n+1} = \eta(\xi(y_1) + \ldots + \xi(y_n)), \quad y_i > 0,$$

where $\xi = \eta^{-1}$. On this submanifold the metric is positive-definite and thus Riemannian.

Curvature of the Dirichlet manifold

Theorem

The Dirichlet manifold has everywhere negative sectional curvature.

Elements of proof :

• A basis of tangent vectors of T_yS is defined by

$$e_i = \frac{\partial}{\partial y_i} + \sqrt{\frac{f \circ \xi(y_i)}{f \circ \xi(y_{n+1})}} \frac{\partial}{\partial y_{n+1}}, \quad i = 1, \dots, n,$$

• The shape operator of $S = \Phi(M)$ has components

$$\langle \nabla_{e_i} N, e_j \rangle = \frac{1}{2\sqrt{f(t) - \sum_{\ell=1}^n f(x_\ell)}} \left(f'(x_i) \delta_{ij} - \frac{f'(t)}{f(t)} \sqrt{f(x_i)f(x_j)} \right).$$

- The second fundamental form $\mathrm{II}(U,V) = \langle -\nabla_U N, V \rangle$ is positive-definite.
- The sectional curvature is, for U, V tangent to the submanifold

$$K(U,V) = \bar{K}(U,V) - \frac{\mathrm{II}(U,U)\mathrm{II}(V,V) - \mathrm{II}(U,V)^2}{\langle U,U\rangle \langle V,V\rangle - \langle U,V\rangle^2},$$

The result follows from $ar{K}=0$ and the Cauchy-Schwarz inequality.

Conclusion

Future work :

- Bigger datasets
- Numerical efficiency

The code is available in Python library geomstats : computing and statistics on manifolds : https://github.com/geomstats/geomstats

Thank you for your attention !